

## Employment

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**AI Engineer** **VinAI** **Jul 2022 - Nov 2023**

**Homezone Parking:** Deployed the Visual Simultaneous Localization and Mapping (VSLAM) module in the initial product demo.

- Addressed scale ambiguity in monocular VSLAM by incorporating wheel odometry information.
- Achieved a 3x runtime reduction in extracting visual features by implementing the algorithm on CUDA.
- Developed a visualization tool for testing and debugging in cars.

**Fully Automated Parking Assistant:**

- Implemented temporal fused mapping module to improve mapping accuracy with noisy input.

**Surrounding View Monitoring:**

- Implemented a real-time four-image denoising module using OpenGL-shader.
- Deployed deep learning image enhancer on mobile with a custom 3D lookup table operator in TFLite.

**AI Resident** **VinAI** **Oct 2020 - Jul 2022**

Conducted research on improving image/video quality in extreme lighting conditions

- Developed unsupervised method achieving 16 FPS inference on mobile, applied as a preprocessor to enhance face detector performance by 26% in low-light conditions.
- Published the new method at WACV 2023 and received a **Best Paper Honorable Mention Award**.

**Research Assistant** **Vietnam National University** **Jun 2019 - Oct 2020**

Conducted research on automatic parallelization for C/C++ programs.

- Developed a program to identify hindering factors and published findings as a publication.
- Designed architecture and algorithms for an automatic program parallelization framework.

## Education

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**Toronto, Canada** **York University** **Jan 2024**

- Master in Computer Science
- Research topic: AI-based image restoration.

**Hanoi, Vietnam** **Vietnam National University** **Sep 2017 - Jun 2021**

- B.S in Information Technology. GPA: 3.86/4.00 (ranked 3rd in university).
- Thesis: Handwritten text generation with stroke vectorization and augmentation.

## Languages and Technologies

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- **Programming:** Python, C/C++, OpenGL, CUDA Programing.
- **Software & Tools:** Pytorch, Tensorflow, TFLite, OpenCV, ROS, RTI-DDS.

## Additional Projects

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**Domain adaptation for vision tasks under adverse weather conditions:** A novel input representation for deep learning models, enabling them to learn weather-invariant features..

## Awards

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- **First Prize, Code War Championship.** Applied complicated algorithms and data structures to solve Competitive Programming problems.
- **First Prize, FPT Digital Race - Qualifying Round.** Applied traditional image processing algorithms and path planning techniques to program the car drive in simulated environment and race track.
- **Student with highest university entrance score.**